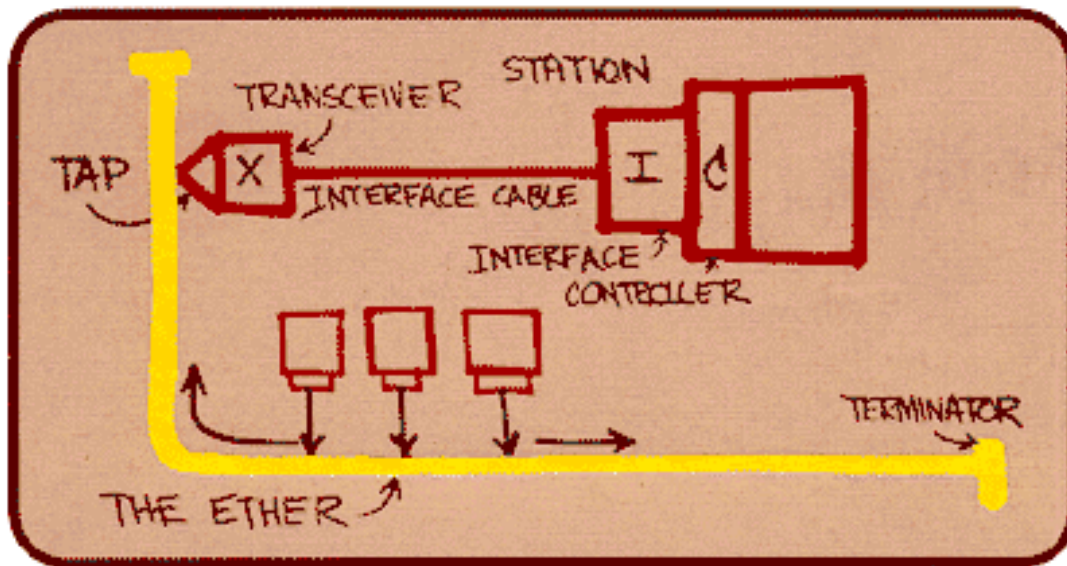


Randomization

- Randomization used in many protocols
- We'll study examples:
 - Ethernet multiple access protocol
 - Reliable multicast
 - Router (de)synchronization
 - Switch scheduling
 - Active queue management

Ethernet

- ❑ Single shared broadcast channel
- ❑ 2+ simultaneous transmissions by nodes: interference
 - ❑ only one node can send successfully at a time
- ❑ Multiple access protocol: Distributed algorithm that determines how nodes share channel, i.e., determine when node can transmit



Metcalfe's Ethernet sketch

Deterministic algorithms

- ❑ Time Division Multiplexing ?
- ❑ Polling?
- ❑ Virtual Ring?

Ethernet: uses CSMA/CD

A: sense channel, **if** idle

then {

transmit and monitor the channel;

If detect another transmission

then {

abort and send jam signal;

update # collisions;

delay as required by exponential backoff algorithm;

goto A

}

else {done with the frame; set collisions to zero}

}

else {wait until ongoing transmission is over and **goto A**}

Ethernet's CSMA/CD (more)

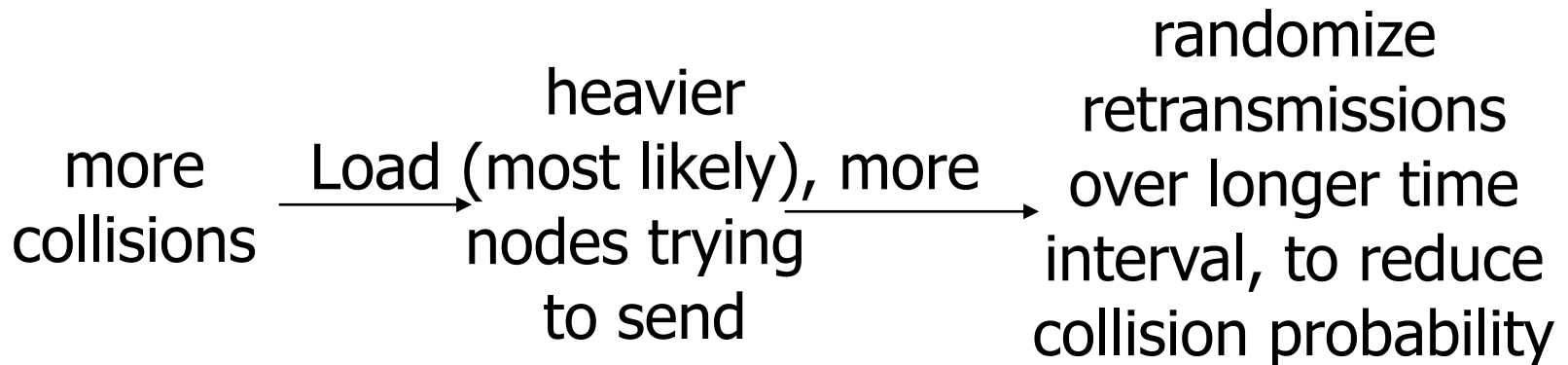
Jam Signal: Make sure all other transmitters are aware of collision; 48 bits;

Exponential Backoff:

- ❑ First collision for given packet: choose K randomly from $\{0,1\}$; delay is $K \times 512$ bit transmission times
- ❑ After second collision: choose K randomly from $\{0,1,2,3\}$...
- ❑ After ten or more collisions, choose K randomly from $\{0,1,2,3,4,\dots,1023\}$

Ethernet's use of randomization

- ❑ *Resulting behavior:* Probability of retransmission attempt (equivalently length of randomization interval) adapted to current load
 - ❑ simple, load-adaptive, multiple access



Ethernet comments

- ❑ Upper bounding at $1023 = k$ limits max size
- ❑ Could remember last value of K when we were successful (analogy: TCP remembers last values of congestion window size)
- ❑ Q: Why use binary backoff rather than something more sophisticated such as AIMD in TCP congestion control: simplicity
 - ❑ Note: Ethernet does multiplicative-increase-complete-decrease

The bottom line

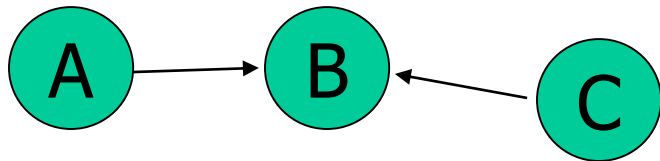
- Why does Ethernet use randomization:
To desynchronize:

A distributed adaptive algorithm to spread out load over time when there is contention for multiple access channel.

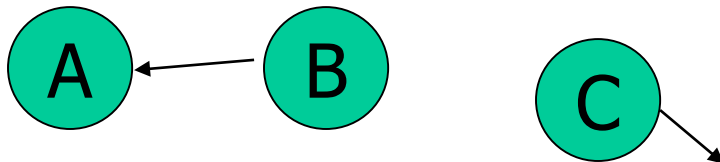
Excursion: What if wireless?!

Typical wireless networks...:

- ❑ are **not full-duplex** (just one channel)
- ❑ nodes **cannot sense** the medium during own transmissions (just one antenna...)
- ❑ no bounded propagation domain
- ❑ are **multihop** (**hidden** and **exposed terminal problems**):



Hidden terminal: C does not notice that B is currently receiving transmissions from A also => no „remote carrier sense“



Exposed terminal: B sends A and C wants to send to someone on the right: it waits because it hears B, but B would not reach the recipient of C, so actually C could send! => inefficient

Excursion: Wireless MAC?

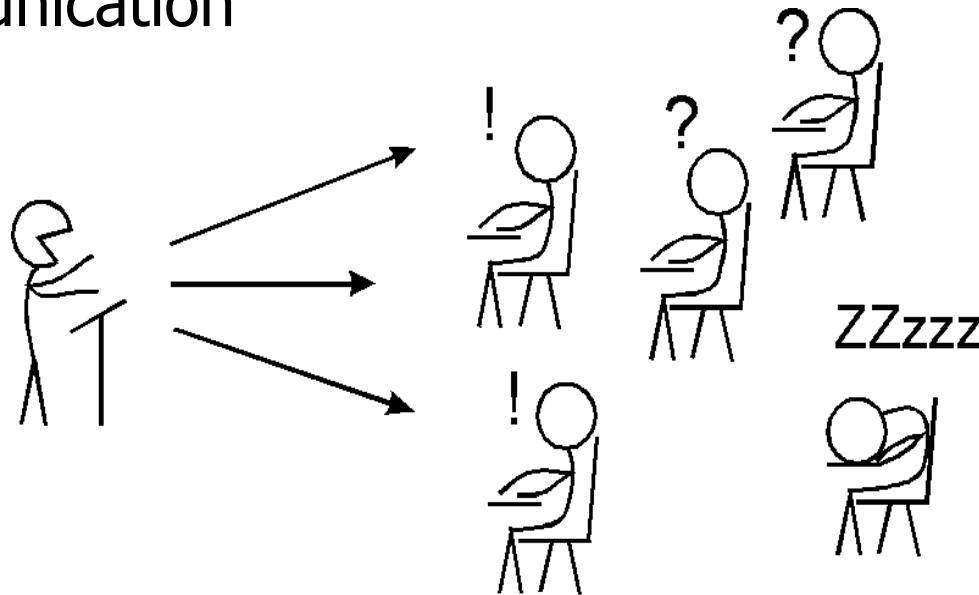
Therefore, CD is often replaced by (best effort) **Collision Avoidance** (CA, cf *DIFS/SIFS* etc.)

Still ongoing research, e.g., there are randomized distributed medium access protocols which optimally coordinate medium access probabilities and exploit the unpredictable non-jammed (e.g., due to external interference) time periods (e.g., the **Jade protocol**).

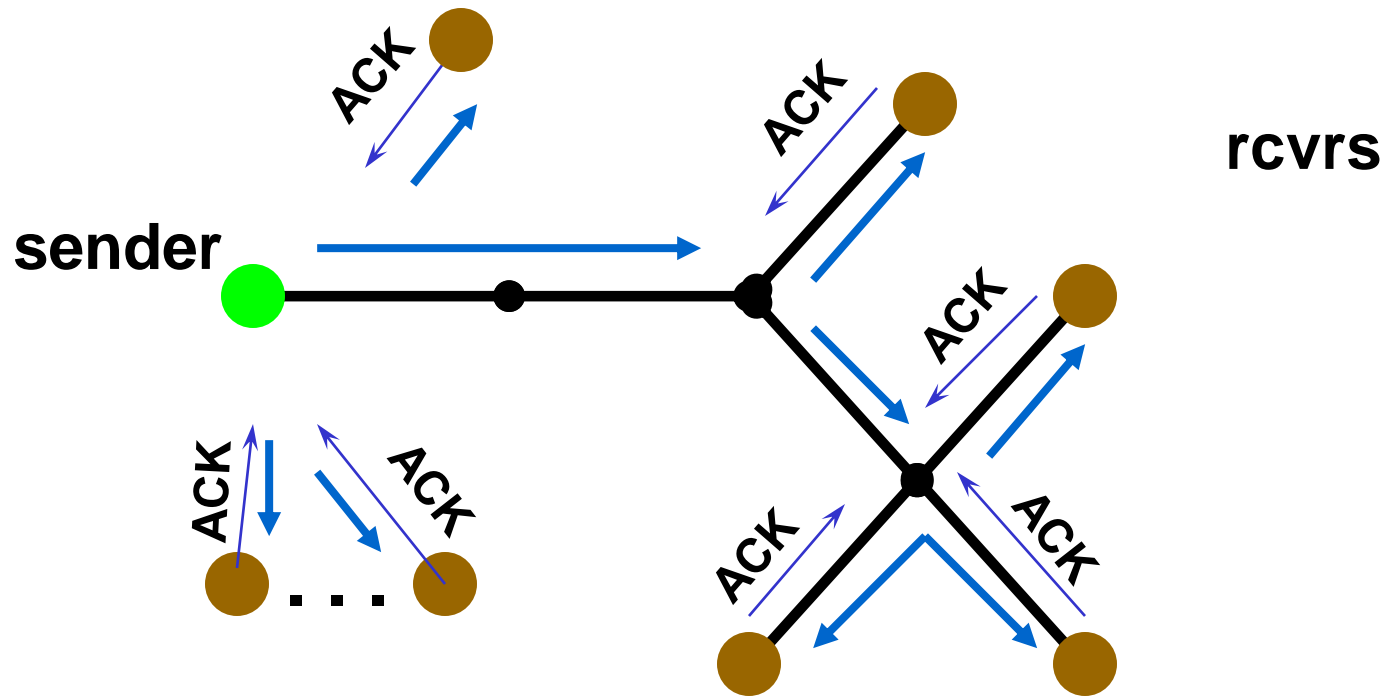
A Jamming-Resistant MAC Protocol for Multi-Hop Wireless Networks, DISC 2010.

Randomization in Reliable Multicast

- ❑ **RM:** How to transfer data “reliably” from source(s) to R receivers.
- ❑ **Conjecture:** All current RM error and congestion control approaches have an analogy in human-human communication



Scalability: Feedback Implosion



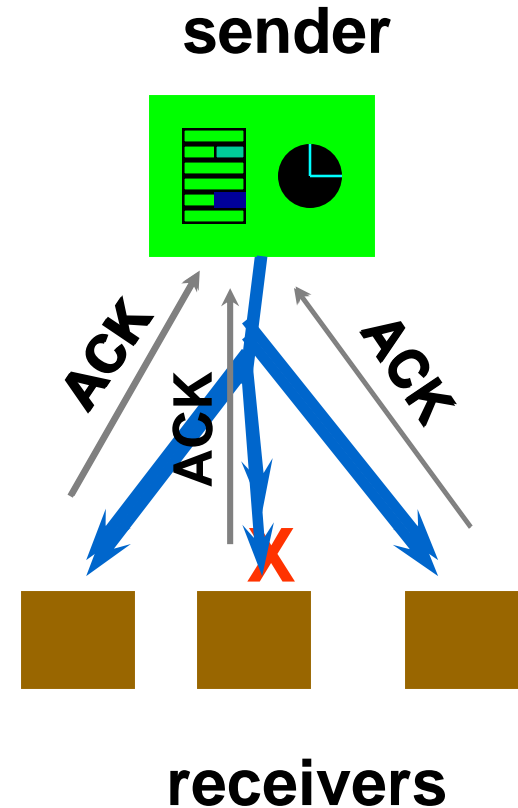
Sender Oriented Reliable Mcast

Sender:

- ❑ mcasts all (re)transmissions
- ❑ selective repeat
- ❑ timers for loss detection
- ❑ ACK table
- ❑ pkt removed when *all* ACKs are in

Rcvr: ACKs received pkts

Note: Group membership important



(Simple) Rcvr Oriented Reliable Mcast

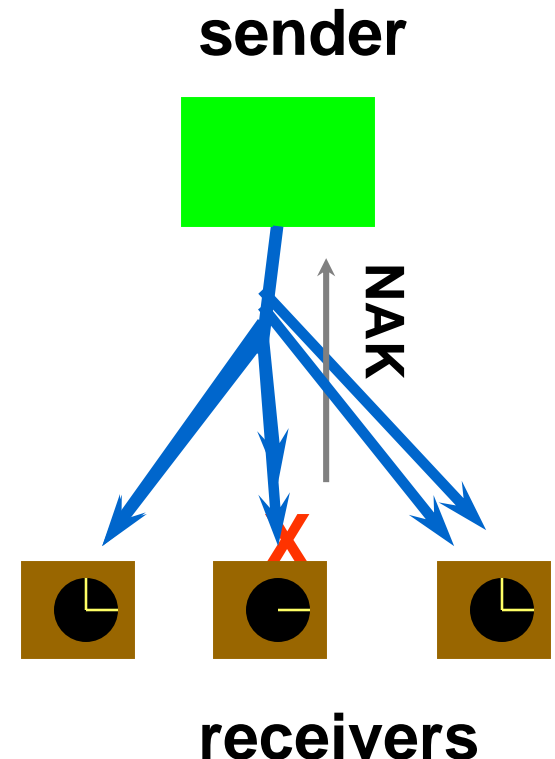
Sender:

- ❑ mcasts (re)transmissions
- ❑ selective repeat
- ❑ responds to NAKs
- ❑ when no longer buffer pkt?

Rcvr:

- ❑ NAKs (unicast to sender) missing pkts
- ❑ timer to detect lost retransmission

Note: easy to allow joins/leaves



Receiver- versus sender-oriented RM: observations

Rcvr-oriented: Shift recovery burden to rcvrs

- ❑ Loss detection “responsibility”, timers
- ❑ Scaling: computational power grow as R grows
- ❑ Weaker notion of “group”
- ❑ Receivers can transparently choose different reliability semantics

But

- ❑ When does sender “release” data rcvd by all?
- ❑ Heartbeat needed to detect lost last pkt

RM: Coping with Scale, Heterogeneity

Issues:

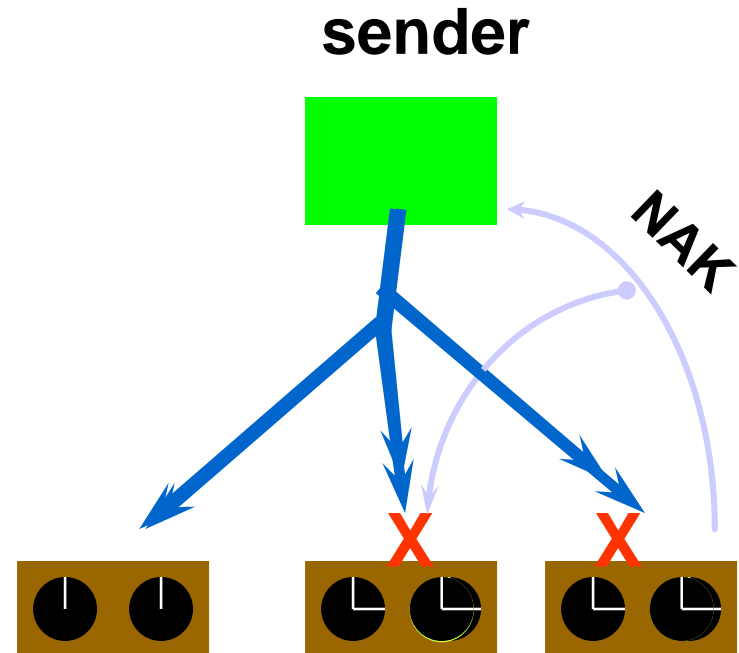
- ❑ Avoid feedback implosion in reverse path
- ❑ Avoid receiving unneeded data (retrans.) in forward path
- ❑ Recover data quickly, avoid long repair times

Techniques:

- ❑ Feedback suppression
- ❑ Local recovery

Feedback suppression

- ❑ Randomly delay NAKs
 - ❑ “Listen” to NAKs generated by others
 - ❑ If no NAK for lost pkt when timer expires, multicast NAK
- ❑ Widely used in RM
- ❑ Tradeoffs
 - ❑ Reduces bandwidth
 - ❑ Additional complexity at receivers (timers, etc)



Reliable multicast (SRM)

Use of randomization

- ❑ Avoid synchronizing all replies
- ❑ To reduce feedback implosion
- ❑ In local recovery, to reduce number of retransmissions of same message.
- ❑ Could scale the randomization interval to be load-adaptive.