

Approximate Duality of Multicommodity Multiroute Cuts and Flows: Multilevel Ball Growing

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Multicommodity Multiroute Cut

Input

- graph $G = (V, E)$ with edge capacities $c : E \rightarrow \mathbb{R}_+$
- k commodities specified by pairs $(s_1, t_1), \dots, (s_k, t_k) \subseteq V^2$
- integer parameter h

Output

- a subset of edges $F \subseteq E$ such that
no pair (s_i, t_i) is connected by h edge-disjoint paths in $(V, E \setminus F)$

Objective

- find a cut of minimum size, that is,
minimize $\sum_{e \in F} c(e)$ subject to “ F is an h -route cut”

Linear Programming Formulation

Notation

- Q_i - the set of all tuples of h edge-disjoint paths between s_i and t_i
- $Q = \bigcup_{i=1}^k Q_i$

Minimum Cut

LP(1)

$$\min \sum_{e \in E} c(e) \cdot x(e)$$

$$\sum_{e \in q} x(e) \geq 1 \quad \forall q \in Q$$

$$x(e) \in \{0, 1\} \quad \forall e \in E$$

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Maximum Flow

$$\max \sum_{q \in Q} f(q)$$

$$\sum_{q \in Q: e \in q} f(q) \leq h \cdot c(e) \quad \forall e \in E$$

$$f(q) \geq 0 \quad \forall q \in Q$$

Observation

- The two LP's are **dual**.
- ⇒ By LP-duality, an upper bound on the **integrality gap** of LP(1) implies an **approximate duality** of the MM-flows and MM-cuts.

Better Linear Programming Formulation

- \mathcal{P}_i - the set of all **paths** between s_i and t_i

Minimum Cut

LP(2)

$$\min \sum_{e \in E} c(e)x(e)$$

$$\sum_{e \in p} (x(e) + x_i(e)) \geq 1 \quad \forall i \in [k], p \in \mathcal{P}_i$$

$$\sum_{e \in E} x_i(e) \leq h - 1 \quad \forall i \in [k]$$

$$x(e), x_i(e) \in \{0, 1\} \quad \forall e \in E, \forall i \in [k]$$

Comparison with LP(1)

- + stronger for $h = 1$, LP(1)=LP(2)
- + induces easier structure
(simple paths vs. tuples of edge-disjoint paths)
- no clear relation to the maximum multiroute flow

New Results

Theorem

- The *integrality gap* of the LP(2) is $O(2^{2h} \log^3 k)$.
- The LP(2) is stronger than the LP(1) by a *factor of h* at most.

Corollary

- *Approximate Duality* of multicommodity multiroute cuts and flows.

Previous Results

Duality of Flows and Cuts (Ford and Fulkerson, 1956)

$$\text{max-flow} = \text{min-cut}$$

Approximate Duality for Multicommodity Flows (FOCS'88, STOC'93)

$$\text{max-flow} \leq \text{min-cut} \leq O(\log k) \text{max-flow}$$

Approximate Duality for Multiroute Flows

- **Single source, uniform capacities:** factor $2h$ (SODA 2008)
- General setting
 - $h = 2$: factor $O(\log^2 n \log k)$ (Chekuri and Khanna, ICALP 2008)
 - $h = 3$: factor $O(\log^3 k)$ (K. and Scheideler, STACS 2011)
- Related results (Barman and Chawla, SODA 2010)
 - integrality gap of LP(2) is $O(\log^2 k)$
 - in case of single commodity - the gap is 2

High Level Description of Rounding Algorithms

Algorithm for Single Source Cut

Input: graph G , fractional solution $x, x_1, \dots, x_k \in \mathcal{R}^{|E|}$ of the LP(2)

$F := \emptyset$

while exists h -connected pair (s, t_i) **do**

with the help of x and x_i , **find a cheap cut F_i for (s, t_i) in G**

$F := F \cup F_i$

update G (e.g., $G := G \setminus F_i$)

return F

This presentation

- How to obtain **from a fractional solution** of the LP(2) the **cheap cuts** F_1, \dots, F_k .
- ⇒ Upper bound on the **integrality gap** of the LP(2).
- ⇒ **Approximate duality**.

Finite Metric Spaces and the LPs

Shortest path metric

$h = 1$

$d(u, v)$ = length of the **shortest path** between u and v in G ,
with respect to x

Universal metric for all commodities - used by Garg et al.

Potential metric

$h \geq 2$

Personal metric for each commodity:

$$d_i(u, v) = |y_i(u) - y_i(v)|$$

where $y_i(w)$ = length of the shortest path between t_i and w ,
with respect to $x + x_i$

Basic properties

- $d_i(s, t_i) \geq 1$
- $\forall uv \in E : d_i(u, v) \leq x(u, v) + x_i(u, v)$

Balls, Cuts and Volume for $h = 1$

Focus on **iteration i**

Key notions

For $r \in [0, 1/2]$ define:

$$\text{ball } B(r) = \{u \in V \mid d(t_i, u) \leq r\}$$

$$\text{cut } \delta(r) = \{uv \in E \mid u \in B(r), v \notin B(r)\}$$

$$\text{cut size } C(r) = \sum_{e \in \delta(r)} c(e)$$

$$\text{volume } V(r) = \frac{\phi}{k} + \int_0^r C(\rho) d\rho \quad \text{where } \phi = \text{OPT}(LP(2))$$

Observation

$$V'(r) = C(r)$$

Ball Growing Technique for $h = 1$

Key ideas

- Allow **only cuts around balls** - $\delta(r)$.
- **Charge the cost** $C(r)$ of the cut $\delta(r)$ **to the volume** $V(r)$ of the ball $B(r)$.
- The quantity $\phi = \sum_{e \in E} x(e)c(e)$ - **volume of the entire graph** - is a **lower bound** on the optimal cut.
- The cut $\delta(r)$ separates the graph into two **independent parts**.
- Always **remove the ball** $B(r)$ from the graph.

Lemma (Garg et al., 1993)

There always **exists a radius** $r < 1/2$ such that

$$C(r) \leq \log k \cdot V(r)$$

Note: No commodity fits in a ball with radius $r < 1/2$.

Ball Growing and the Calculus Behind

Lemma (Ball Growing)

If two functions f and g defined on \mathcal{R} satisfy

- f is a *nondecreasing* function on \mathcal{R} and $f > 0$,
- f is *differentiable* on \mathcal{R} ,
- $\forall r \in \mathcal{R}, g(r) \leq f'(r)$,

then there *exists* $r \in \mathcal{R}$ such that

$$g(r) \leq \frac{1}{|\mathcal{R}|} \log \frac{f(r_{\max})}{f(r_{\min})} \cdot f(r).$$

Lemma (Garg et al., 1993)

The functions volume $f(r) = V(r)$ and cost $g(r) = C(r)$ satisfy for $\mathcal{R} = [0, 1/2)$ the assumptions of the lemma and $f(r_{\max})/f(r_{\min}) \leq k$.

\Rightarrow the radius r from the lemma provides a *cheap cut* for $h = 1$

Ball Growing for Multiroute Cuts

Difficulty for $h \geq 2$

- **Cuts must be redefined** - no approximation algorithm with finite approximation ratio can afford to perform $\delta(r)$ cuts.

How to fix it?

- Think about **edge** e as about a segment consisting of **two parts**: **x_i -part** of length $x_i(e)$ and **x -part** of length $x(e)$.
- **Only edges** crossing the border of $B(r)$ in x -part belong to **cut**.
- **Only x -parts** of edges contribute to the **volume**.
- **Both parts** of every edge - $x(e) + x_i(e)$ - contribute to **distances**.

Cuts and Volume Revisited

Assumption

- The x_i -part precedes (on the way from t_i) the x -part.

Key notions

$$\text{cut } \delta_x(r) = \{uv \in E \mid y_i(u) + x_i(u, v) \leq r < y_i(v)\}$$

$$\delta_{x_i}(r) = \{uv \in E \mid y_i(u) \leq r < y_i(u) + x(u, v)\}$$

$$\text{cut size } C(r) = c(\delta_x(r))$$

$$\text{volume } V(r) = \phi/k + \int_{\rho \in [0, r]} C(\rho) d\rho$$

Observation

- $V'(r) = C(r)$
- $\delta_x(r) \cup \delta_{x_i}(r) = \delta(r)$
- If $|\delta_{x_i}(r)| \leq h - 1$, then $\delta_x(r)$ is an h -route cut.

Ball Growing Technique for $h = 2$

Basic Notation

- A radius $r \in [0, 1]$ is **forbidden** if $|\delta_{x_i}(r)| > h - 1$.
- $\mathcal{R} = \{r \in [0, 1] \mid \delta_{x_i} \leq h - 1\}$

Lemma (Forbidden Radii)

The size of the set \mathcal{R} of good radii is at least $1/h$.

Proof:

- $\mu = |\{r \in [0, 1] \mid |\delta_{x_i}(r)| \geq h\}|$
- Recall that $\sum_{e \in E} x_i(e) \leq h - 1$.
- Therefore, $h \cdot \mu \leq \sum_{e \in E} x_i(e) \leq h - 1$ and hence, $\mu \leq 1 - 1/h$.

Consequence

Ball Growing Lemma: good radius r with $c(\delta_x(r)) \leq h \log k \cdot V(r)$.

Ball Growing Technique for $h = 2$, cont'd

Single Source Case

- For each t_i , find ball $B(r)$ with h -route cut $c(\delta_x(r)) \leq h \log k \cdot V(r)$.
- All t_j 's with $t_j \in B(r)$ are **done as well**.
- For all t_j 's with $t_j \notin B(r)$: no path from t_j to s through $B(r)$ as at most one edge is leaving $B(r)$, so $B(r)$ can be removed.

Multiple Source Case

Problem: Many source-destination pairs in ball $B(r)$ of t_i .

Solution:

- Recall that $\mathcal{R} = \{r \in [0, 1] \mid |\delta_{x_i}(r)| \leq h - 1\}$ and that $|\mathcal{R}| \geq 1/h$.
- Cut \mathcal{R} into \mathcal{R}_1 and \mathcal{R}_2 of size $1/(2h)$.
- Grow balls from t_i and s_j with radii r_1 and r_2 .
- Charge volume of that ball with the smaller # (s_j, t_j) -pairs.
- Continue recursively in ball and outside part of G .

Ball Growing Technique for $h = 3$

Another Difficulty for $h = 3$

Even if we know how to find a cheap 3-route cut, the 3-route cut **does not split the 3-route cut problem into independent problems**.

Reason: Some t_j can have a path to s_j leading through the ball of (s_j, t_j) .

How to fix it? Multilevel ball growing

- Allow edges to be **charged several times**, yet
- Ensure that **no edge is charged too often**. How???
- Maintain a counter **level $\ell(e)$** for every edge - how many times e was charged for some cut.
- When growing a new ball, **avoid edges with high level**.

Multilevel Ball Growing

Pessimistic scenario

- Construct a ball for commodity 1 and perform corresponding cut.
 - Construct a new ball for commodity 2, perform corresponding cut; accidentally, the **new ball contains the previous ball** inside.
 - Construct a new ball for commodity 3, perform corresponding cut; accidentally, the **new ball contains the previous ball** inside again.
 - etc.
- ⇒ The **level** of some edges is k at the end - **too much**.

Idea

- Whenever a ball of **level ℓ** is included in a new ball, make sure there are at least **two balls** of level ℓ that are **included**.
- ⇒ The **maximum level** of an edge is **$\log k$** .

Multilevel Ball Growing, cont'd

D - set of balls from previous iterations

Partitioning of D in iteration i

- D_1 - for every level ℓ , the ball of level ℓ that is the **closest to t_i**
- $D_2 = D \setminus D_1$

Good radii - first attempt

$$\mathcal{R} = \{r \in [0, 1] \mid |\delta_{x_i}(r)| \leq h - 1 \text{ and } \delta_x(r) \cap E(D_1) = \emptyset\}$$

Note that $V'(r) = C(r)$, for $V(r) = \phi/k + \int_{\rho \in \mathcal{R} \cap [0, r]} C(\rho) d\rho$

\Rightarrow **Ball growing lemma applies:**

$$\exists r \in \mathcal{R} \text{ s.t. } C(r) \leq \frac{1}{|\mathcal{R}|} \log k \cdot V(r)$$

However: how large is \mathcal{R} ?? Might be **too small** \Rightarrow bound too weak.

How to make the set of good radii large?

Restricted Diameter Lemma

- **Entry edges** $in_E(H)$ of ball B : edges that connect B to rest of G .
- **Entry nodes** $in_V(H)$ of ball B : outside nodes of entry edges.

Lemma: If x -diameter of entry nodes of ball B is at least $1/(2h \log k)$ then the cost of the mincut of the entry nodes in H is at most $2h \log k \cdot Vol(B)$.

- If lemma applies to ball B , B is cut into two halves with at most one entry edge, so these halves can be removed from G .
- So we are only left with balls B with **small** diameter.
- Thus, diameters of all balls in D_1 sum up to at most $1/(2h)$.
- This implies that **size of good radii** shrinks from at least $1/h$ to **at least $1/(2h)$** .

Still, general multi-source 3-route cut problem very tricky...

How to make the set of good radii large? Case $h \geq 3$.

Definition: The radius r is **blocked by H** if $\delta_x(r) \cap E(H) \neq \emptyset$.

Lemma

For every $H \in D_1$ there exists a subset $F_H \subseteq E(H)$ such that the measure of the set of **radii blocked by $H \setminus F_H$** is small and

$$\sum_{e \in F_H} c(e) \leq O(2^{2h} \log k) \sum_{e \in E(H)} x(e)c(e).$$

- For $h = 3$ - F_H is a simple cut separating the two entry points of the ball H ; by doing this, H can be removed from D and G .
 - For $h > 3$ - substantially more complicated: we have to **increase the level** for each $e \in E(H)$ to reflect that H is charged for the removal of F_H .
- ⇒ New problem: how to keep the **levels under control**? Credit ...

Restricted Structures

Basic definitions

- A **restricted structure** H is an induced subgraph of G .
- **Entry edges** $in_E(H)$ of H - edges that connect H to the rest of G .
- The **level** of a restricted structure H is

$$\ell(H) = \max\{\ell(e) \mid e \in E(H) \setminus \bigcup_{H' \in D(H)} E(H')\}. \quad (1)$$

where $D(H) = \{H' \in D \mid H' \subsetneq H\}$.

- The **credit** of a restricted structure H is

$$\phi(H) = 2^{2|in_E(H)| + \ell(H)}. \quad (2)$$

- For each level ℓ , put to D_ℓ the minimum number of restricted structures of level ℓ whose credit sums up to at least $2h^2 2^{2h+\ell}$, starting with the closest to t_j .

Restricted Structures, cont'd.

Invariant

At the end of iteration i the structures in D form a *laminar family* such that for all $H \in D$

$$|in_E(H)| \leq h - 1, \quad (3)$$

$$\sum_{H \in D} \phi(H) \leq i \cdot 2^{2h}. \quad (4)$$

Lemma

If the Invariant holds, then

- at the end of iteration i , $\ell(e) \leq 2h + \log i$ for every edge e ,
- for each level ℓ , $\sum_{H \in D_1: \ell(H)=\ell} |in_E(H)| \leq h^2 2^{2h-1}$.

Many Good Radii - Crucial Lemma

Lemma

For every $H \in D_1$ there is a subset $F_H \subseteq E(H)$ and a subset $I_H \subseteq R_H$ so that for $H' = H \setminus F_H$,

$$\int_{r \in R_H \setminus I_H} |\text{mincut}_{H'}(r)| dr \leq \sum_{e \in E(H)} x_i(e), \quad (5)$$

$$\sum_{e \in F_H} c(e) = O(h^6 2^{2h}) \sum_{e \in E(H)} x(e) c(e), \quad (6)$$

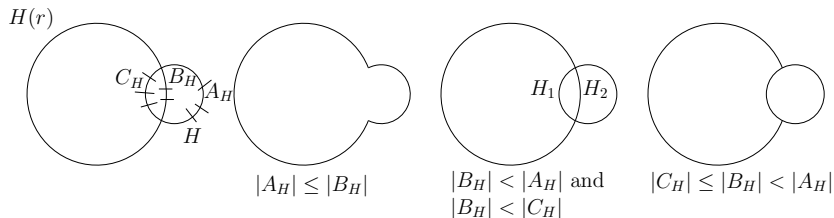
$$|I_H| \leq 1/(h^3 2^{2h} \log k). \quad (7)$$

Other Difficulties with the Balls

Laminar sets

For previous lemma, the set D has to satisfy the **laminar property**:
for any two $H_1, H_2 \in D$: $H_1 \subset H_2$, or $H_2 \subset H_1$, or $H_1 \cap H_2 = \emptyset$.

To maintain the laminar property, a special care must be given to **old balls intersecting with the border** of the new ball:



Conclusion

Disclaimer

- Plenty of details skipped ...

Open problems

- Improve the **upper bound** on the factor in the approximate duality.
- Improve the **lower bound** on the factor in the approximate duality.
- Find a **better approximation** algorithm for the multicommodity multiroute cut problem.
- Apply the **multilevel ball growing** technique to other problems ...